

Splitting factor maps into u - and s -bijective maps.

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- 1 Dynamical systems
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- 3 Problem
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- 5 Finding factor maps that split

1st example-Shifts of finite type

Let G be a finite directed graph which consists of a vertex set G^0 , an edge set G^1 , and two maps $r, s : G^1 \rightarrow G^0$. The source vertex of edge e is given by $s(e)$ and the range vertex is given by $r(e)$.

Definition

We define

$$\Sigma_G = \{(x_n)_{n \in \mathbb{Z}} \mid x_n \in G^1, r(x_n) = s(x_{n+1}) \text{ for all } n \text{ in } \mathbb{Z}\}$$

With the left shift map $\sigma : \Sigma_G \rightarrow \Sigma_G$,

$$\sigma(x)_n = x_{n+1}.$$

2nd example: Hyperbolic toral automorphism

$$\text{Let } \hat{A} = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}$$

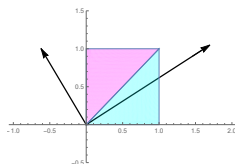
Define $A : \mathbb{T}^2 \rightarrow \mathbb{T}^2$ by

$$A([x]) = [\hat{A}x]$$

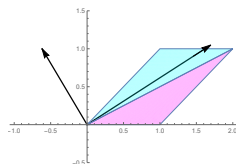
where x is in \mathbb{R}^2 and $[x]$ denotes its equivalence class in $\mathbb{T}^2 = \mathbb{R}^2/\mathbb{Z}^2$. By the integer components and the determinant, A is an invertible map.

Eigenvalues : γ and $-\gamma^{-1}$, where $\gamma = \frac{1+\sqrt{5}}{2} > 1$.

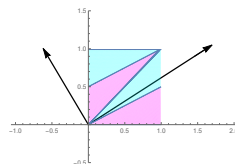
Eigenvectors: $v_u = \begin{bmatrix} \gamma \\ 1 \end{bmatrix}$ and $v_s = \begin{bmatrix} -\gamma^{-1} \\ 1 \end{bmatrix}$.



\hat{A}



$\text{mod } \mathbb{Z}^2$



Notice $\mathbb{R}^2 = \{tv_u \mid t \in \mathbb{R}\} \oplus \{tv_s \mid t \in \mathbb{R}\} = E^u \oplus E^s$

For general \hat{A} in $GL_d(\mathbb{R})$ we define,

$$E^s = \{x \in \mathbb{R}^d \mid \|\hat{A}^n x\| \rightarrow 0, n \rightarrow +\infty\}$$

$$E^u = \{x \in \mathbb{R}^d \mid \|\hat{A}^n x\| \rightarrow 0, n \rightarrow -\infty\}$$

Definition

We say a matrix \hat{A} is **hyperbolic** if \hat{A} is in $GL_d(\mathbb{R})$ and,

$$\mathbb{R}^d = E^s \oplus E^u.$$

With these in mind, the A from our example, is a hyperbolic toral automorphism.

Globally: Let f be a homeomorphism.

Definition

We say two points x, y in X are **stably equivalent** and write $x \stackrel{s}{\sim} y$ if

$$\lim_{n \rightarrow +\infty} d(f^n(x), f^n(y)) = 0$$

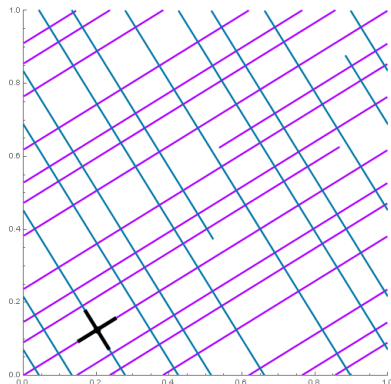
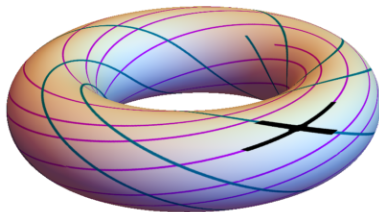
We let $X^s(x)$, the set of y with $x \stackrel{s}{\sim} y$.

We say that x, y are **unstably equivalent** and write $x \stackrel{u}{\sim} y$ if

$$\lim_{n \rightarrow -\infty} d(f^n(x), f^n(y)) = 0$$

We let $X^u(x)$ be the set of y with $x \stackrel{u}{\sim} y$.

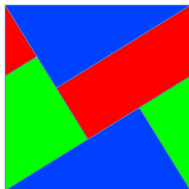
On a hyperbolic toral automorphism the global unstable and stable sets wrap around densely.



The local stable and unstable sets are given by moving a little bit along the eigendirections. Locally, \mathbb{T}^2 can be viewed as $\mathbb{R} \times \mathbb{R}$.

The HTA can be modeled using symbolic dynamics by way of Markov partitions, where $\pi : (\Sigma_G, \sigma) \rightarrow (\mathbb{T}^n, A)$ is a finite-to-one factor map.

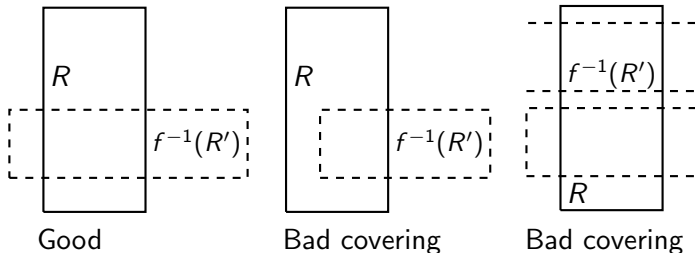
- Adler and Weiss 1967 for the case of dimension $d = 2$.
- Sinai 1968 any finite dimension d .
- Bowen 1970, for basic sets of Axiom A diffeomorphisms.



Markov Property

When $\text{int}(R) \cap f^{-1}(\text{int}(R'))$ is non-empty, then for all x in R and y in $f^{-1}(R')$, $[y, x]$ is defined and we have,

$$[f^{-1}(R'), R] = f^{-1}(R') \cap R.$$

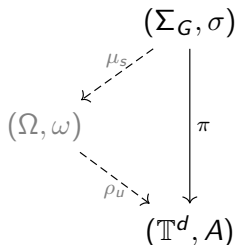


Definition

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Definition

We say that $\pi : (X, f) \rightarrow (Y, g)$ is **s-bijective** if, for any x in X , its restriction to $X^s(x)$ is a bijection to $Y^s(\pi(x))$.

Theorem

Let $\pi : (X, f) \rightarrow (Y, g)$ be an s-bijective map. Then for every x in X , the map $\pi : X^s(x, \epsilon) \rightarrow Y^s(\pi(x), \epsilon')$ is a local homeomorphism.

A u -bijective map is defined and characterized analogously.

Given (\mathbb{T}^d, A) , we can find a factor map π .

$$\begin{array}{c} (\Sigma_G, \sigma) \\ \downarrow \pi \\ (\mathbb{T}^d, A) \end{array}$$

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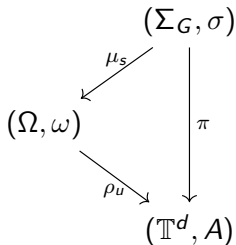
locally represented as,

$$\begin{array}{c} \text{Cantor} \times \text{Cantor} \\ \downarrow \pi \\ \mathbb{R}^m \times \mathbb{R}^n \cong E^s \times E^u \end{array}$$

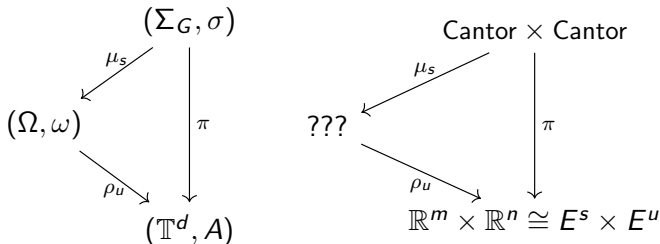
where $m + n = d$.

Note: This map cannot be s -bijective nor u -bijective.

Suppose we also have μ_s , an s -bijective map and ρ_u , a u -bijective map such that,



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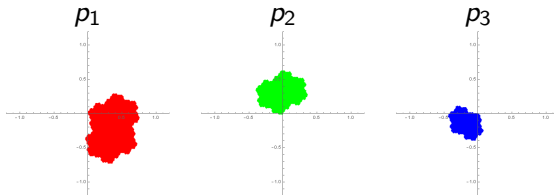


What must $???$ look like locally?

What is a candidate space for $???$?

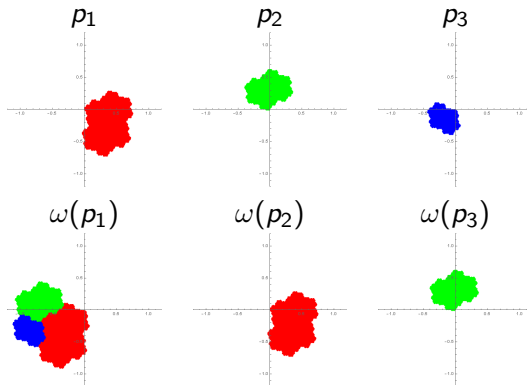
3rd Example: Substitution tiling systems, $(\Omega, \mathcal{P}, \omega)$

Prototiles, $\mathcal{P} = \{p_1, p_2, \dots, p_n\}$. Each $p_i \subseteq \mathbb{R}^d$ is the closure of its interior.



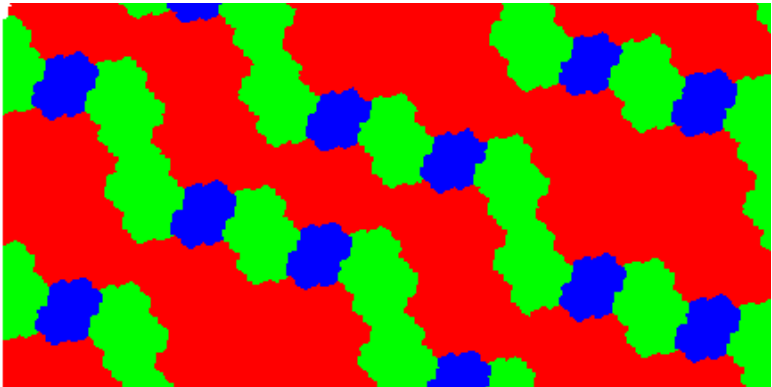
A tile t is a translation of some prototile.

A substitution rule $\omega(p_i)$ that inflates, possibly rotates and subdivides with translates of prototiles.



A partial tiling is a collection of tiles whose interiors are pairwise disjoint. A tiling is a partial tiling whose union is \mathbb{R}^d .
The substitution can be iterated and extended to all tilings.

We define Ω to be the set of tilings T such that if $P \subseteq T$ then $P \subseteq \omega^k(t)$ for some tile t .

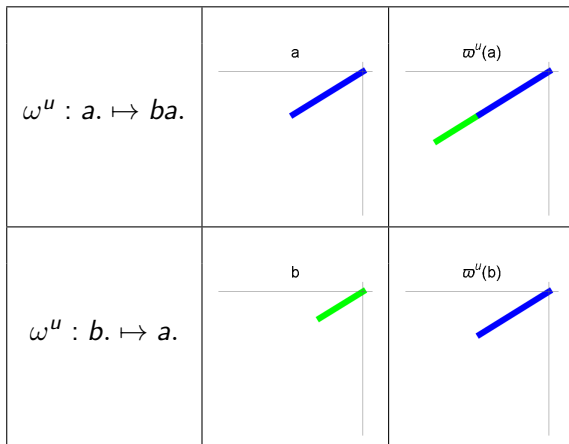


Forcing the border

Definition

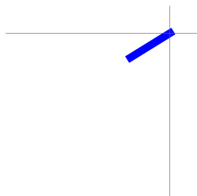
A tiling system $(\Omega, \mathcal{P}, \omega)$ **forces its border** if there is a $k \geq 1$ such that, if T and T' are two tilings containing a tile t , then the patches in $\omega^k(T)$ and $\omega^k(T')$ consisting of all tiles which meet $\omega^k(t)$ are identical.

Tiling example 2-Fibonacci

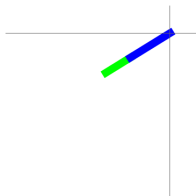


ω^u : Does not force border ($a \mapsto ba$ and $b \mapsto a$)

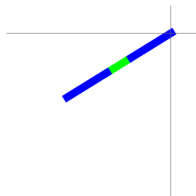
a.



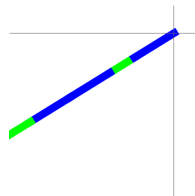
ba.



aba.

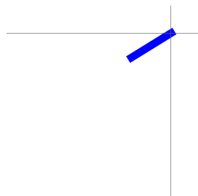


baaba.

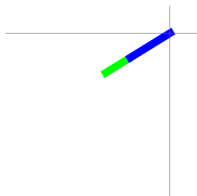


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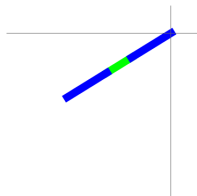
a.



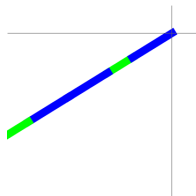
ba.



aba.



baaba.

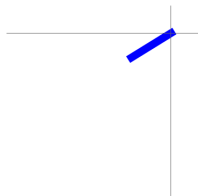


Extend on the right by a
 $\dots babaa \boxed{b} a. \boxed{a} \dots$

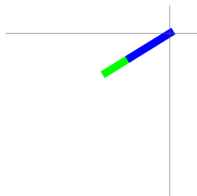
Extend on the right by b
 $\dots babaa \boxed{b} a. \boxed{b} \dots$

ω^u : Does not force border ($a \mapsto ba$ and $b \mapsto a$)

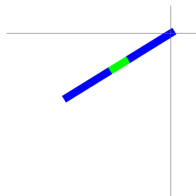
a.



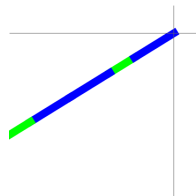
ba.



aba.



baaba.



Extend on the right by a

$\dots babaa \boxed{b} a. \boxed{a} \dots$

ω^u

$\dots baba \boxed{a} ba. \boxed{b} a \dots$

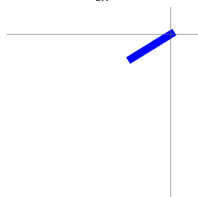
Extend on the right by b

$\dots babaa \boxed{b} a. \boxed{b} \dots$

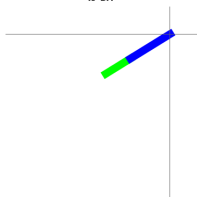
$\dots baba \boxed{a} ba. \boxed{a} \dots$

ω^u : Does not force border ($a \mapsto ba$ and $b \mapsto a$)

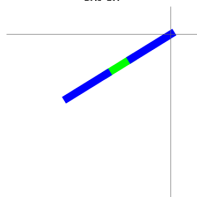
a.



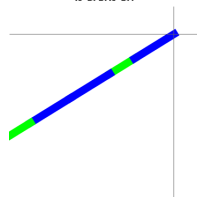
ba.



aba.



baaba.



Extend on the right by a

$\dots babaa \boxed{b} a. \boxed{a} \dots$

$\dots baba \boxed{a} ba. \boxed{b} a \dots$

$\dots bab \boxed{a} aba. \boxed{a} ba \dots$

ω^u
 $(\omega^u)^2$

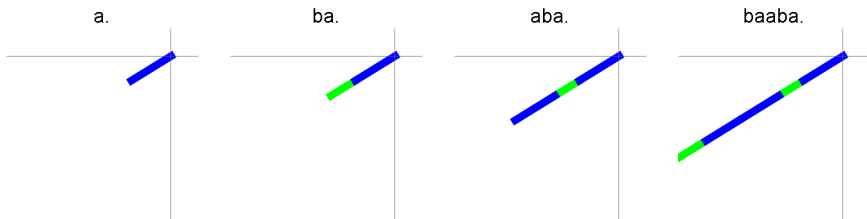
Extend on the right by b

$\dots babaa \boxed{b} a. \boxed{b} \dots$

$\dots baba \boxed{a} ba. \boxed{a} \dots$

$\dots bab \boxed{a} aba. \boxed{b} a \dots$

ω^u : Does not force border ($a \mapsto ba$ and $b \mapsto a$)



Extend on the right by a

ω^u

$(\omega^u)^2$

$(\omega^u)^3$

... babaa b a. a ...

... baba a ba. b a ...

... bab a aba. a ba ...

... b a baaba. b aba ...

Extend on the right by b

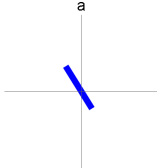
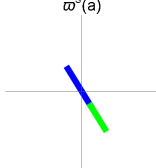
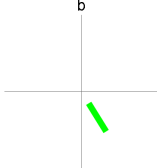
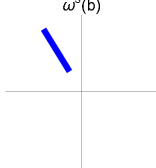
... babaa b a. b ...

... baba a ba. a ...

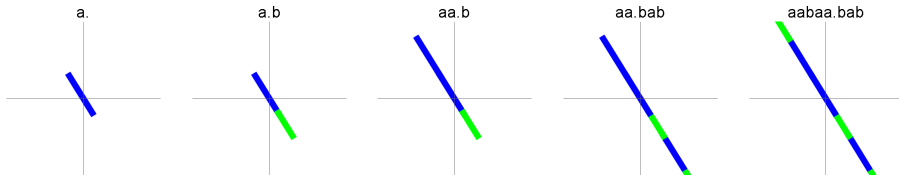
... bab a aba. b a ...

... b a baaba. a ba ...

Tiling example 3: Also Fibonacci

$\omega^s : a \mapsto (-1)b.a$	 <p>A 2D coordinate system with a vertical axis. A blue line segment is drawn in the second quadrant, sloping downwards from left to right. The label 'a' is placed above the vertical axis.</p>	 <p>A 2D coordinate system with a vertical axis. A blue line segment is in the second quadrant and a green line segment is in the fourth quadrant, both sloping downwards from left to right. The label $\omega^s(a)$ is placed above the vertical axis.</p>
$\omega^s : .b \mapsto (-1).a$	 <p>A 2D coordinate system with a vertical axis. A green line segment is drawn in the fourth quadrant, sloping downwards from left to right. The label 'b' is placed above the vertical axis.</p>	 <p>A 2D coordinate system with a vertical axis. A blue line segment is drawn in the second quadrant, sloping downwards from left to right. The label $\omega^s(.b)$ is placed above the vertical axis.</p>

ω^s : Does force border ($a \mapsto (-1)b.a$ and $b \mapsto (-1)a.$)

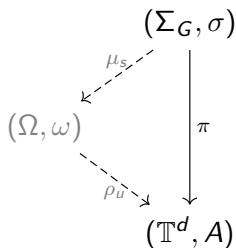


Definition

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Is there a necessary and sufficient condition for a given factor map, π , to have a splitting?

Theorem

If a splitting for the factor map $\pi : \Sigma \rightarrow \mathbb{T}^d$ exists then,

for every x in \mathbb{R}^d for which $q(x)$ is periodic in \mathbb{T}^d , there exist open sets $U \subseteq E^s$ and $V \subseteq E^u$ containing 0, with the property that for all y and \bar{y} in $V \setminus (\partial^u \mathcal{R} - x)$,

$$U \cap (\partial^s \mathcal{R} - y - x) = U \cap (\partial^s \mathcal{R} - \bar{y} - x).$$

To understand the condition, let us first define \mathcal{R} .

Constructing \mathcal{R}

Let $\nu : G^1 \rightarrow \mathbb{Z}^d$ be a labelling of the edges of a finite graph G .
 Let $\nu(e)^s$ be the projection onto E^s through E^u .

Define $\pi^s : \Sigma_G \rightarrow E^s$ by,

$$\pi^s(x) = \sum_{n \leq 0} \hat{A}^{-n} \nu(x_n)^s$$

Define $\pi^u : \Sigma_G \rightarrow E^u$ by,

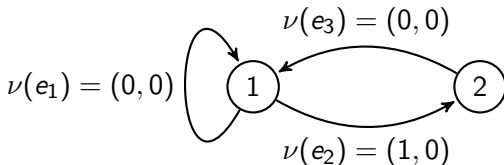
$$\pi^u(x) = - \sum_{n \geq 1} \hat{A}^{-n} \nu(x_n)^u$$

and $\pi' : \Sigma_G \rightarrow \mathbb{R}^d$ by,

$$\pi'(x) = \pi^s(x) + \pi^u(x) \in \mathbb{R}^d$$

Let G_{fib} be the following finite directed graph with labelling map,

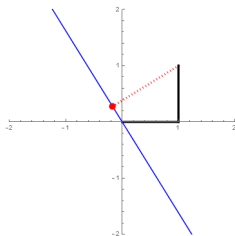
$$\nu : G_{\text{fib}}^1 \rightarrow \mathbb{Z}^2.$$



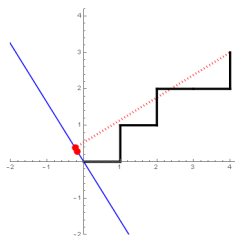
Suppose we take $x = \dots e_2 e_3 e_2 e_3 e_2 e_3 . e_2 e_3 e_2 e_3 e_2 e_3 \dots$ from $\Sigma_{G_{\text{fib}}}$.

Visualizing the map π^s

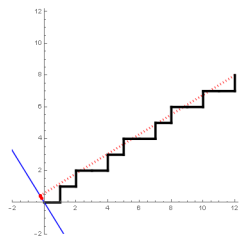
$$\pi^s(x) = \sum_{n \leq 0} A^{-n} \nu(x_n)^s = \lim_{k \rightarrow \infty} \left(\sum_{n=0}^{-k} A^{-n} \nu(x_n) \right)^s$$



$k=1$



$k=3$



$k=5$

Markov partition

Definition

Let $\mathcal{R}_{G,\nu}$ be defined by the following sets, for $i \in G^0$,

$$R_i^s = \pi^s \{x \in \Sigma_G \mid r(x_0) = i\} \subseteq E^s$$

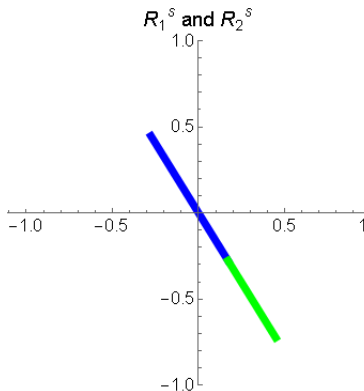
$$R_i^u = \pi^u \{x \in \Sigma_G \mid r(x_0) = i\} \subseteq E^u$$

and

$$\mathcal{R}_{G,\nu} = \{R_i^s + R_i^u \mid i \in G^0\}$$

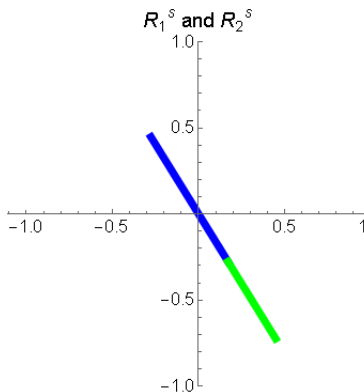
$$\begin{aligned}
 R_1^s &= \pi^s \{x \in \Sigma_{G_{\text{fib}}} \mid r(x_0) = 1\} \\
 &= \left\{ \sum_{n \geq 0} a_n (-\gamma)^{-n} (1, 0)^s \mid \begin{array}{l} a_n \in \{0, 1\} \\ a_n a_{n+1} = 0 \\ a_0 = 0 \end{array} \right\} \\
 &= \text{blue set}
 \end{aligned}$$

$$\begin{aligned}
 R_2^s &= \pi^s \{x \in \Sigma_{G_{\text{fib}}} \mid r(x_0) = 2\} \\
 &= \left\{ \sum_{n \geq 0} a_n (-\gamma)^{-n} (1, 0)^s \mid \begin{array}{l} a_n \in \{0, 1\} \\ a_n a_{n+1} = 0 \\ a_0 = 1 \end{array} \right\} \\
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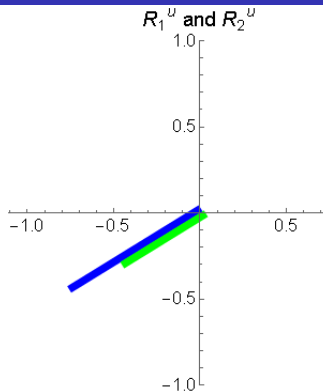
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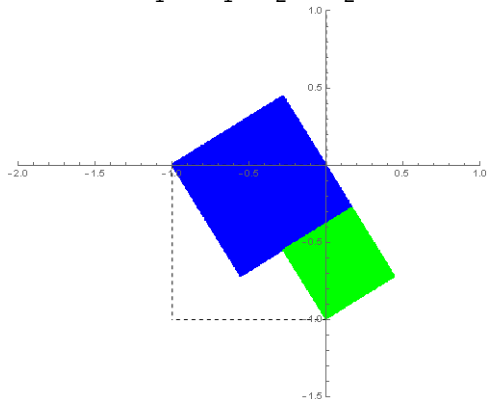


$$\begin{aligned}
 R_1^u &= \pi^u \{x \in \Sigma_{G_{\text{fib}}} \mid r(x_0) = 1\} \\
 &= \left\{ -\sum_{n \geq 1} a_n(\gamma)^n (1, 0)^u \mid \begin{array}{l} a_n \in \{0, 1\} \\ a_n a_{n+1} = 0 \end{array} \right\} \\
 &= \text{blue set}
 \end{aligned}$$

$$\begin{aligned}
 R_2^u &= \pi^u \{x \in \Sigma_{G_{\text{fib}}} \mid r(x_0) = 2\} \\
 &= \left\{ -\sum_{n \geq 1} a_n(\gamma)^n (1, 0)^u \mid \begin{array}{l} a_n \in \{0, 1\} \\ a_n a_{n+1} = 0 \\ a_0 = 0 \end{array} \right\} \\
 &= \text{green set}
 \end{aligned}$$

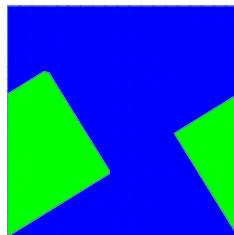


$$R_1^s + R_1^u, R_2^s + R_2^u$$



\mathcal{R}

$$q : \mathbb{R}^2 \rightarrow \mathbb{T}^2 \bmod \mathbb{Z}^2 \text{ map.}$$



$q(\mathcal{R})$

Theorem

If \mathcal{R} is regular, the collection $\{R_i + m \mid 1 \leq i \leq I, m \in \mathbb{Z}^d\}$ are pairwise disjoint and tile \mathbb{R}^d then,

- 1 The map $\pi = q \circ \pi' : \Sigma_G \rightarrow \mathbb{T}^d$ is a finite-to-one factor map.
- 2 $q(\mathcal{R})$ is a Markov partition.
- 3 There is a dense G_δ in \mathbb{T}^d , B , such that if x is in B then $\#\pi^{-1}\{x\} = 1$.

Graph Iterated Function system property

Theorem

The collection of sets $\mathcal{R}_{(G,\nu)}$ satisfies the following equations,

$$AR_i^u = \bigcup_{s(e)=i} R_{r(e)}^u - \nu(e)^u,$$

$$R_j^s = \bigcup_{r(e)=j} AR_{r(e)}^s + \nu(e)^s,$$

for $1 \leq i, j \leq I$.

Theorem

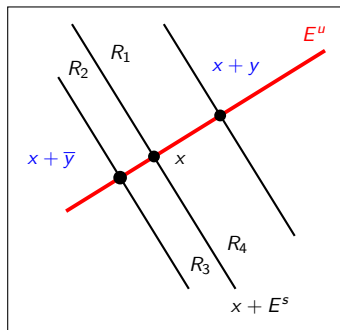
If a splitting for the factor map $\pi : \Sigma \rightarrow \mathbb{T}^d$ exists then,

for every x in \mathbb{R}^d for which $q(x)$ is periodic in \mathbb{T}^d , there exist open sets $U \subseteq E^s$ and $V \subseteq E^u$ containing 0, with the property that for all y and \bar{y} in $V \setminus (\partial^u \mathcal{R} - x)$,

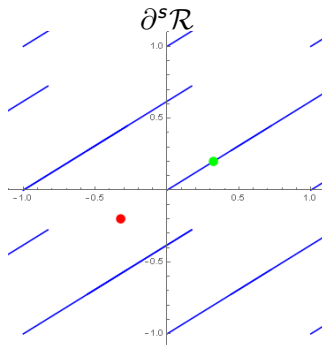
$$U \cap (\partial^s \mathcal{R} - y - x) = U \cap (\partial^s \mathcal{R} - \bar{y} - x).$$

The stable boundaries around a periodic point (for the map A) should look the same in the E^u direction.

The condition is satisfied if the boundary around a periodic point looks something like this...

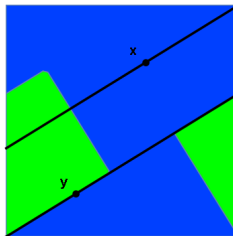


Our G_{fib} example does not satisfy the condition



Idea for proof

Suppose the condition fails.



Choose x and y unstably equivalent and stably equivalent to a periodic point, where x has one preimage under π while y has two preimages under π . Contradicts properties of u and s -bijective maps. No splitting for the map $\pi : \Sigma_{G_{\text{fib}}} \rightarrow \mathbb{T}^2$ exists.

Does there exist another SFT for which the factor map splits?

Theorem (Putnam, 2005)

Let (Y, g) be an irreducible Smale space. Then there exists a shift of finite type (Σ, σ) , another irreducible Smale space (Ω, ω) , and


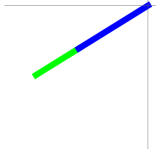

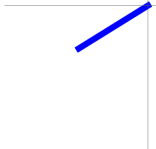
$$\mu : (\Sigma, \sigma) \rightarrow (\Omega, \omega)$$

$$\rho : (\Omega, \omega) \rightarrow (Y, g)$$

factor maps, such that μ is s -bijective and ρ is u -bijective.

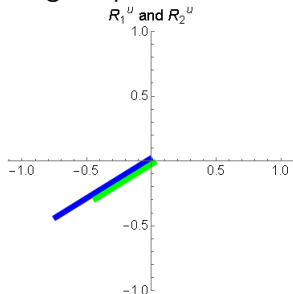
How do we find it, explicitly?

The GIFS for our G_{fib} Markov partition gives a tiling substitution.

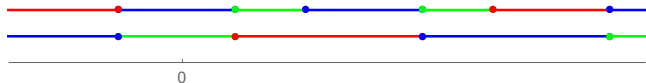
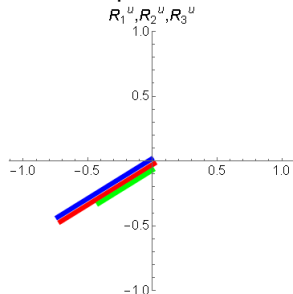
<p>a</p> 	<p>$\varpi^u(a)$</p> 	$AR_1^u = R_1^u \cup R_2^u - (1, 0)^u$
<p>b</p> 	<p>$\varpi^u(b)$</p> 	$AR_2^u = R_1^u$

The collared tiling system $(\Omega_1, \mathcal{P}_1, \omega_1)$ forces its border.

Original prototiles

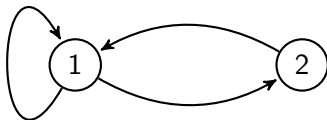


Collared prototiles

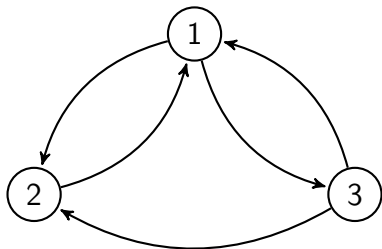


Non-conjugate shifts of finite type

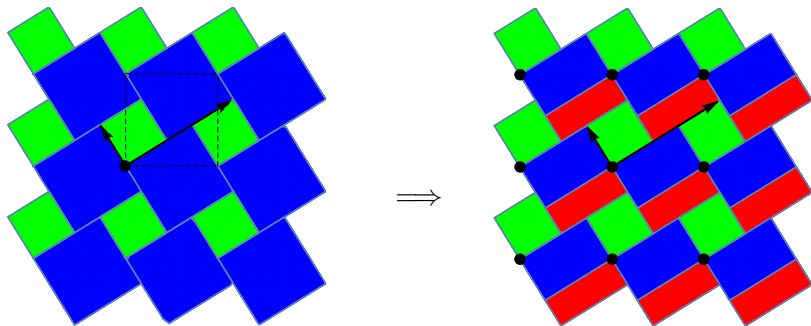
$(\Sigma_{G_{\text{fib}}}, \sigma)$ (old)



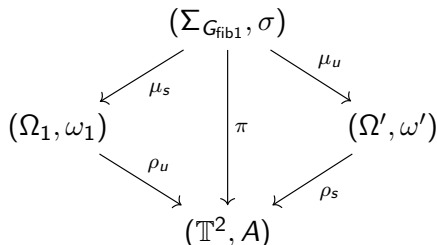
$(\Sigma_{G_{\text{fib1}}}, \sigma)$ (new)



New Markov partition.



From Anderson and Putnam 1998 and Wieler 2005.



(Ω_1, ω_1) collared fibonacci (tiling example 2)

(Ω', ω') collared fibonacci substitution (tiling example 3)

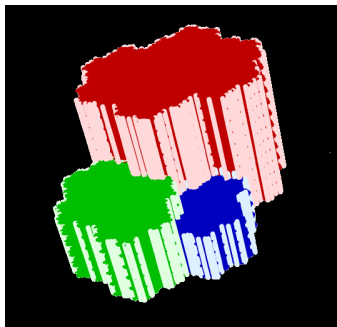
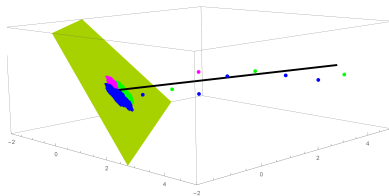
A three dimensional example

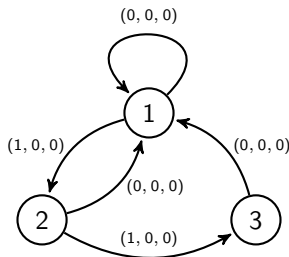
Let $\hat{B} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$. The induced map B defines an HTA of \mathbb{T}^3 .

Eigenvalues: $\beta > 1$, $\alpha, \bar{\alpha}$, where $\beta^3 - \beta^2 - \beta - 1 = 0$.

Expanding line and contracting plane.

The Markov partition is given by the following (viewed in \mathbb{R}^3).





Unstable (Tribonacci)

Stable (Rauzy)

$$AR_1^u = R_1^u \cup R_2^u - (1, 0, 0)^s$$

$$AR_2^u = R_1^u \cup R_3^u - (1, 0, 0)^s$$

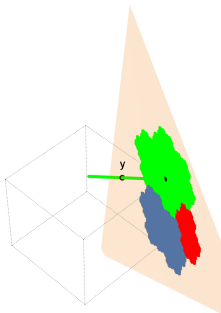
$$AR_3^u = R_1^u$$

$$R_1^s = AR_1^s \cup AR_2^s \cup AR_3^s$$

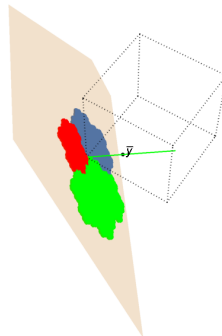
$$R_2^s = AR_1^s + (1, 0, 0)^s$$

$$R_3^s = AR_2^s + (1, 0, 0)^s$$

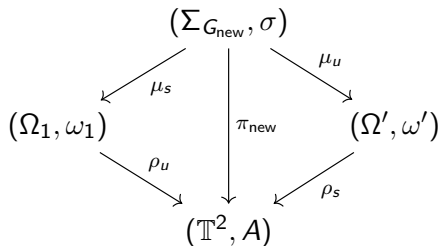
Interior point



Boundary point



No splitting for the factor map exists.



(Ω_1, ω_1) collared tribonacci substitution

(Ω', ω') collared Rauzy substitution (tiling example 1)

We know:

- Existence of splitting for $\pi \implies$ condition on boundaries of MP.
- Forcing the border of $(\Omega, \omega) \implies \exists$ a map π that splits.
- We have an example of a factor map that splits, but the corresponding tiling system (Ω, ω) does not force its border.

Questions:

- Does the condition being satisfied imply the existence of a splitting?
- If we randomly label a graph of the SFT what sort of sets in \mathbb{R}^d are possible? Under which conditions?
- What does all of this have to do with Ian's homology theory for Smale spaces?



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Thank you for your attention!